UpWind

Lidars – better than metmasts?



Mike Courtney - WP6 and DTU



Overview

- •WP6 essentials
- •Lidar state-of-the-art
- Lidar vs metmast
- Conclusions





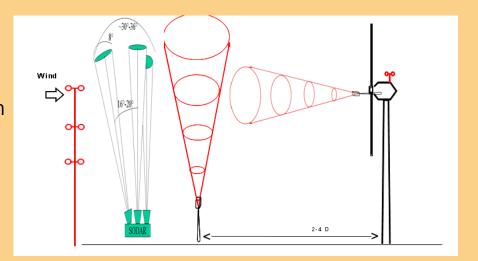


WP6 at a glance - topics

SODARs and LIDARs (=Remote Sensing =RS)

Calibration methods Improvements Bistatic SODARs Mast comparisons – flat and complex terrain Error predictions in complex terrain Sensing turbulence Nacelle mounted lidars Power curve measurements

Introduction of RS to IEC 61400-12 Aerosol statistics



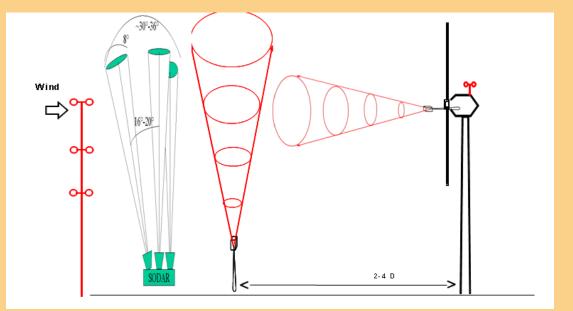




WP6 at a glance - participants

•Risø DTU (WP leader)

- •CENER
- •CRES
- University of Salford
- University of Auckland
- Vestas
- •QinetiQ







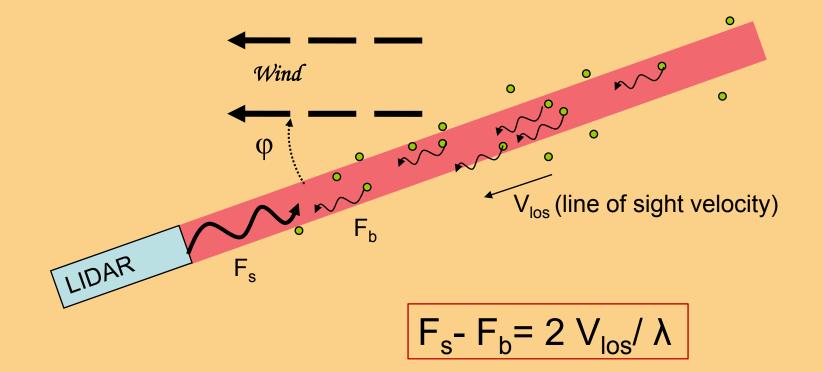
Lidar – state-of-the-art







Basic measuring principle



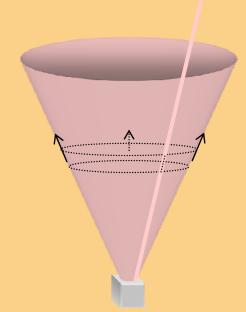




Combining line-of-sight speeds to obtain the horizontal wind speed.



Ideal, no assumptions needed



Practical, we need to assume that the flow is homogeneous





Different lidar types

Leosphere WindCube™

Pulsed

Range-gated

Simultaneous heights

Fixed probe-length

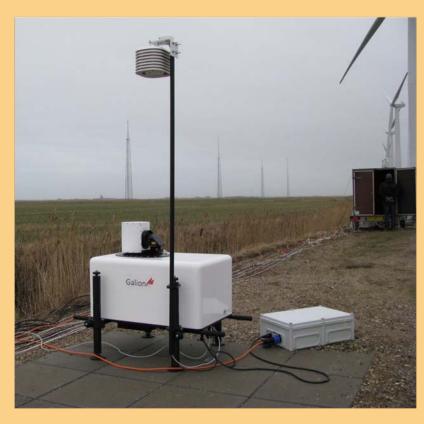


Natural Power
ZephIR™
Continuous
Focused
Sequential heights
Probe-length f(H²)





Newcomers





Gallion

Vindicator





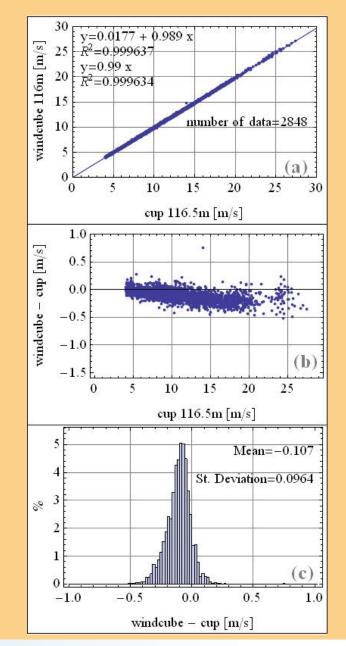
Good lidars are getting accurate - in flat terrain!

Best lidars are within $\pm 1.5\%$ of traceable cup (for the heights we can test).

Very low noise

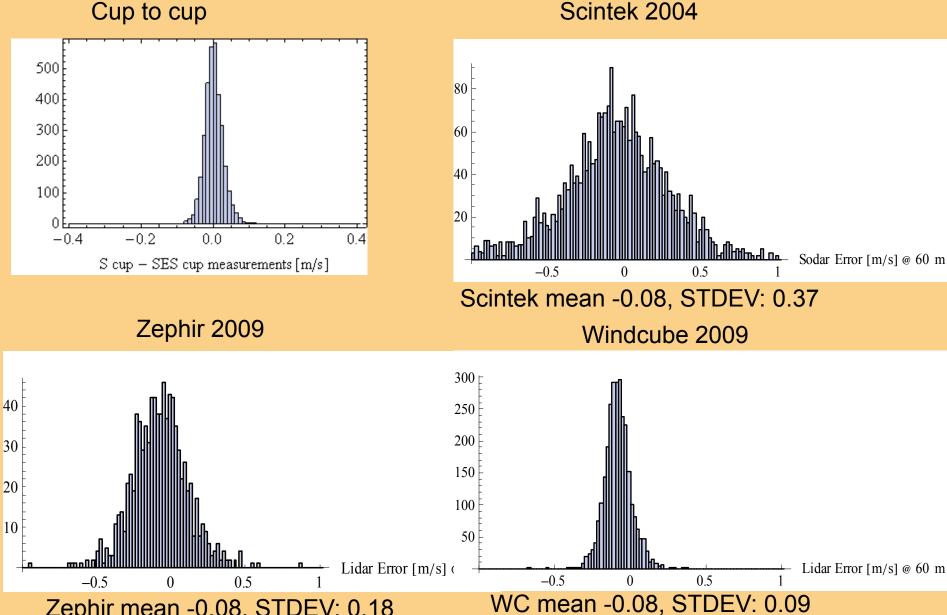
Cup anemometer calibration and cup-mast mounting uncertainties are the limiting constraints for assessing lidar accuracy.





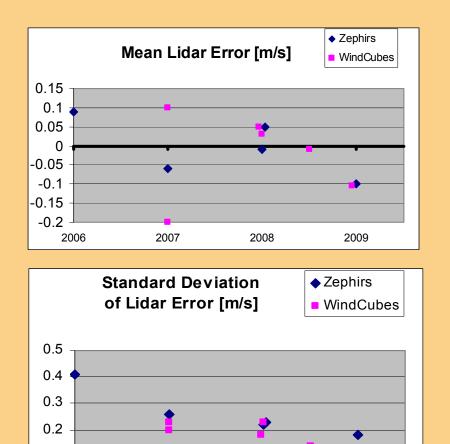


Measurment results for different tested sensors - at 60 m height



Zephir mean -0.08, STDEV: 0.18

Development of Wind Sensing Lidars



2008

2009

2006: Zephir commercial model introduced. Hardware issues.

2007: Ceilometer installed, screening on clouds: positive bias and σ reduced, availability drops. Leosphere introduces Windcube.

2008: Cloud correction: availability increases. Cone angle accuracy: bias reduced.

2008.5: Cone angle accuracy Estimator improved: nonlinear problems reduced.

2009: Improved test conditions, lower RIN. Improved test conditions.

Vindicator and Galion commercial

Mean < ~±0.05 m/s	σ ~0.20
Mean < ~±0.05 m/s	σ ~0.10

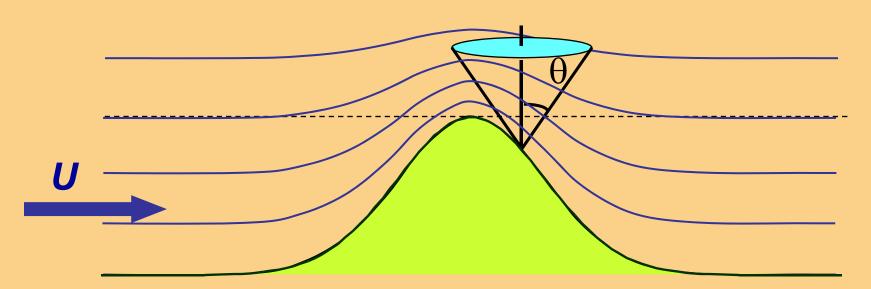


2007

0.1



Complex Terrain – errors!

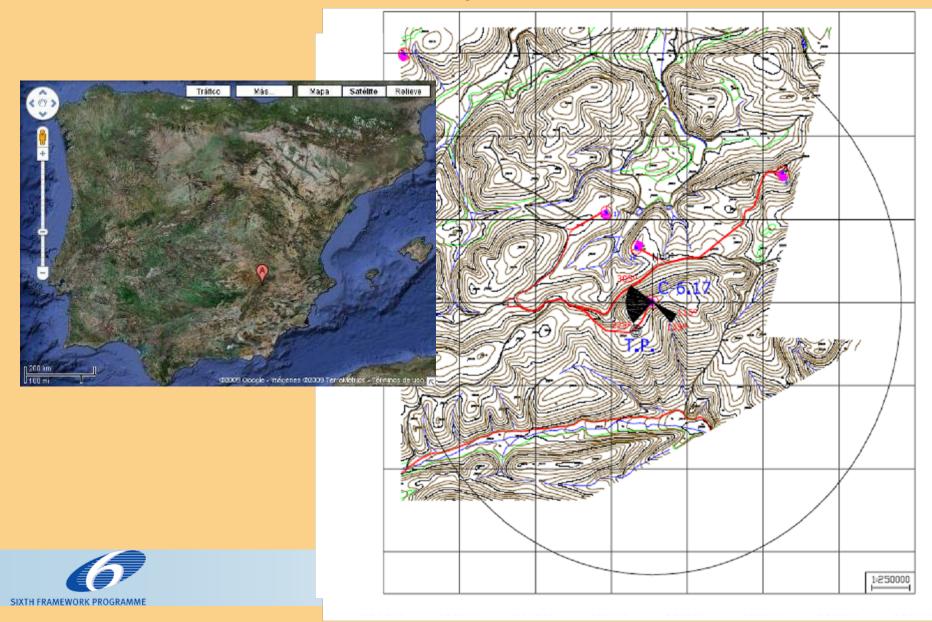


Different parts of cone sample different winds

Example: Dimitri Foussekis CRES

$$V_{\text{LIDAR}} = 0.9995 V_{\text{MAST}} + 0.0194$$
 in flat terrain
 $V_{\text{LIDAR}} = 0.8753 V_{\text{MAST}} + 0.4519$ in complex terrain

Measurements by CENER

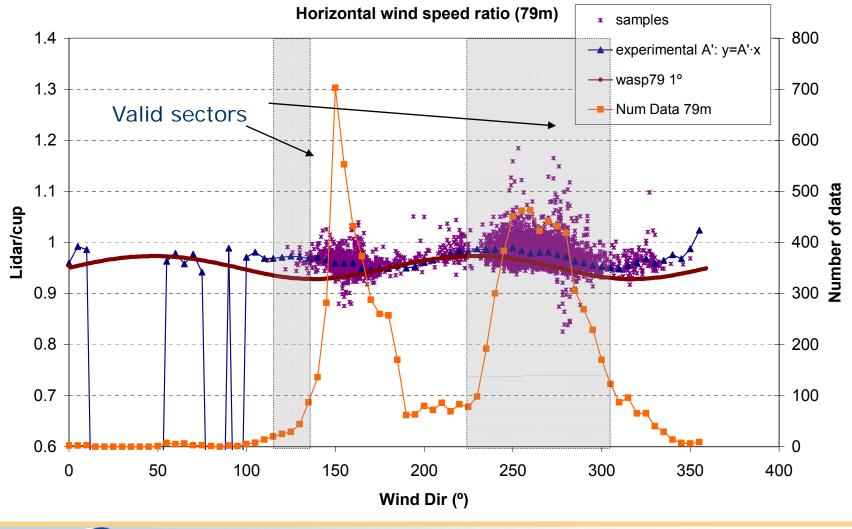








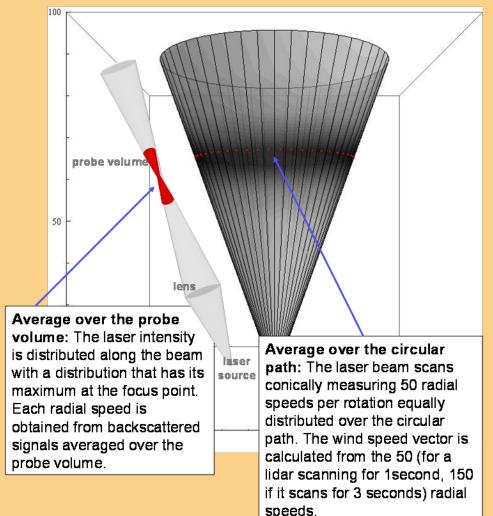
Speed ratios and comparison to WEng

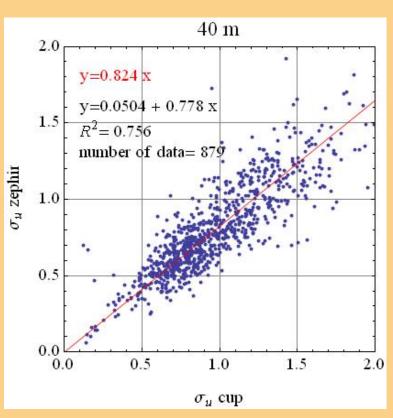






Turbulence sensed by a lidar – spatial attenuation

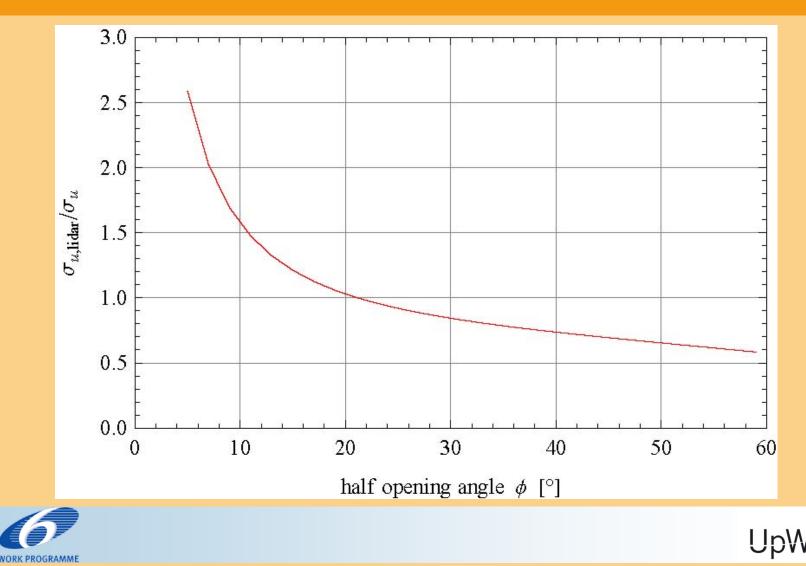




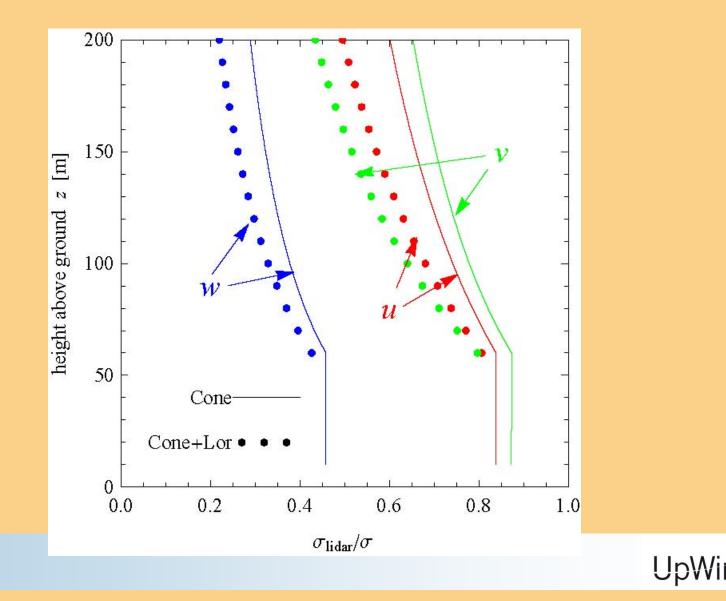




The horizontal variance 'seen' by the lidar depends on the cone angle.



The ratio also varies with height





Lidar vs metmast - accuracy

- Whilst we 'calibrate' lidars using cups, we can never do better than the cup accuracy.
- Many mast measurements are not particularly good
 - Mast shadow and flow distortion
 - Bad calibrations

•Even in complex terrain, cup and lidar errors may well be comparable.

• Lidar verification requirements are driving improvements in cup calibration and mounting techniques.





Lidar vs metmast - price

• Assuming lidars can be used many times, their economics appear promising, especially for replacing high masts.

•There are also 'hidden/forgotten' lidar costs

- Power supply
- Maintenance
- Repairs! (renting might be attractive)

• Well conducted lidar resource measurements should reduce the AEP uncertainty, giving more subtle economic benefits.





Lidars vs metmast - reliability

- No contest!
- Lidars improving but there is still a way to go.





Lidars – wish list

• Traceable accuracy (coming) but preferably without using cups (?).

- Lower price
- Higher reliability
- Lower power consumption (autonomous systems)





Lidars – better than metmasts?

- Accuracy 1-1 (2-1 if shear is important)
- Economics 1-1
- Reliability 0-1
- Flexibility/discretion 1-0





Thanks for listening!



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